DS05-11115-2E

MEMORY Un-buffered

$1 \text{ M} \times 64 \text{ BIT}$ SYNCHRONOUS DYNAMIC RAM SO-DIMM

MB8501S064AE-100/-84/-67

144-pin, 2 Clock, 1-bank, based on 1 M imes 16 Bit SDRAMs with SPD

■ DESCRIPTION

The Fujitsu MB8501S064AE is a fully decoded, CMOS Synchronous Dynamic Random Access Memory (SDRAM) Module consisting of four MB811171622A devices which organized as two banks of 1 M x 16 bits and a 2K-bit serial EEPROM on a 144-pin glass-epoxy substrate.

The MB8501S064AE features a fully synchronous operation referenced to a positive edge clock whereby all operations are synchronized at a clock input which enables high performance and simple user interface coexistence.

The MB8501S064AE is optimized for those applications requiring high speed, high performance and large memory storage, and high density memory organizations.

This module is ideally suited for workstations, PCs, laser printers, and other applications where a simple interface is needed.

■ PRODUCT LINE & FEATURES

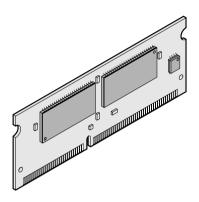
Para	ameter	MB8501S064AE-100	MB8501S064AE-84	MB8501S064AE-67	
Clock Frequency		100 MHz max.	84 MHz max.	67 MHz max.	
Burst Mode Cycle Time		10 ns max. (CL = 3) 15 ns max. (CL = 2)	12 ns max. (CL = 3) 17 ns max. (CL = 2)	15 ns max. (CL = 3) 20 ns max. (CL = 2)	
RAS Access Time		54 ns max.	56 ns max.	60 ns max.	
CAS Access Time		24 ns max.	24 ns max. 26 ns max.		
Output Valid from	Clock	8.5 ns max. (CL = 3) 9 ns max. (CL = 2)	8.5 ns max. (CL = 3) 9 ns max. (CL = 2)	9 ns max. (CL = 3) 10 ns max. (CL = 2)	
Power Burst Mode		1944 mW max. 1800 mW max.		1620 mW max.	
Dissipation	Power Down Mode		28.8 mW max.		

- Unbuffered 144-pin SO-DIMM Socket Type (Lead pitch: 0.8 mm)
- Conformed to JEDEC Standard (2 CLK)
- Organization: 1,048,576 words × 64 bits
- Memory: MB811171622A (1 M × 16, 2-bank) × 4 pcs. Serial Presence Detect (SPD) with Serial EEPROM
- 3.3 V ±0.3 V Supply Voltage
- All input/output LVTTL compatible

- 2048 Refresh Cycle every 32.8 ms
- Auto and Self Refresh
- CKE Power Down Mode
- DQM Byte Masking (Read/Write)
- · Module size:
 - 1.0" (height) \times 2.66" (length) \times 0.15" (thickness)

■ PACKAGE





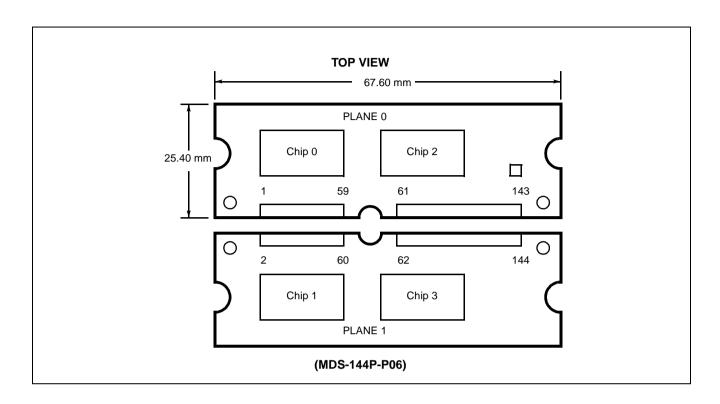
(MDS-144P-P06)

Package and Ordering Information

- 144-pin SO-DIMM, order as MB8501S064AE-xxDG (DG = Gold Pad)

■ PIN ASSIGNMENTS

Pin No.	Signal Name	Pin No.	Signal Name	Pin No.	Signal Name	Pin No.	Signal Name	Pin No.	Signal Name	Pin No.	Signal Name
1	Vss	49	DQ ₁₃	97	DQ ₂₂	2	Vss	50	DQ ₄₅	98	DQ ₅₄
3	DQ ₀	51	DQ ₁₄	99	DQ ₂₃	4	DQ ₃₂	52	DQ ₄₆	100	DQ ₅₅
5	DQ ₁	53	DQ ₁₅	101	Vcc	6	DQ33	54	DQ ₄₇	102	Vcc
7	DQ ₂	55	Vss	103	A 6	8	DQ34	56	Vss	104	A 7
9	DQ ₃	57	N.C.	105	A8	10	DQ ₃₅	58	N.C.	106	BA ₀
11	Vcc	59	N.C.	107	Vss	12	Vcc	60	N.C.	108	Vss
13	DQ4	61	CLK ₀	109	A 9	14	DQ36	62	CKE₀	110	N.C.
15	DQ ₅	63	Vcc	111	A ₁₀	16	DQ ₃₇	64	Vcc	112	N.C.
17	DQ ₆	65	RAS	113	Vcc	18	DQ ₃₈	66	CAS	114	Vcc
19	DQ ₇	67	WE	115	DQMB ₂	20	DQ39	68	N.C.	116	DQMB ₆
21	Vss	69	CS ₀	117	DQMB ₃	22	Vss	70	N.C.	118	DQMB ₇
23	DQMB ₀	71	N.C.	119	Vss	24	DQMB ₄	72	N.C.	120	Vss
25	DQMB ₁	73	N.C.	121	DQ ₂₄	26	DQMB₅	74	CLK ₁	122	DQ ₅₆
27	Vcc	75	Vss	123	DQ ₂₅	28	Vcc	76	Vss	124	DQ ₅₇
29	A ₀	77	N.C.	125	DQ ₂₆	30	A ₃	78	N.C.	126	DQ ₅₈
31	A 1	79	N.C.	127	DQ ₂₇	32	A ₄	80	N.C.	128	DQ59
33	A ₂	81	Vcc	129	Vcc	34	A 5	82	Vcc	130	Vcc
35	Vss	83	DQ ₁₆	131	DQ ₂₈	36	Vss	84	DQ ₄₈	132	DQ ₆₀
37	DQ8	85	DQ17	133	DQ29	38	DQ40	86	DQ49	134	DQ ₆₁
39	DQ ₉	87	DQ ₁₈	135	DQ ₃₀	40	DQ ₄₁	88	DQ ₅₀	136	DQ ₆₂
41	DQ ₁₀	89	DQ19	137	DQ ₃₁	42	DQ ₄₂	90	DQ ₅₁	138	DQ ₆₃
43	DQ ₁₁	91	Vss	139	Vss	44	DQ43	92	Vss	140	Vss
45	Vcc	93	DQ ₂₀	141	SDA	46	Vcc	94	DQ ₅₂	142	SCL
47	DQ ₁₂	95	DQ ₂₁	143	Vcc	48	DQ44	96	DQ53	144	Vcc



■ PIN DESCRIPTIONS

Symbol	I/O	Function	Symbol	I/O	Function
A ₀ to A ₁₀ , BA ₀	I	Address Input	CS₀	I	Chip Select
RAS	I	Row Address Strobe	DQ₀ to DQ₃₃	I/O	Data Input/Data Output
CAS	I	Column Address Strobe	Vcc		Power Supply (+3.3 V)
WE	I	Write Enable	Vss	_	Ground (0 V)
DQMB ₀ to DQMB ₇	I	Data (DQ) Mask	N.C.		No Connection
CLK ₀ , CLK ₁	I	Clock Input	SCL	I	Serial PD Clock
CKE₀	ı	Clock Enable	SDA	I/O	Serial PD Address/Data Input/Output

■ SERIAL-PD INFORMATION

Byte	Function Described		I	Hex Value	•
Буце	Function Described		-100	-84	-67
0	Defines Number of Bytes Written into	128 Byte	80h	80h	80h
	Serial Memory at Module Manufacture				
1	Total Number of Bytes of SPD Memory Device	256 Byte	08h	08h	08h
2	Fundamental Memory Type	SDRAM	04h	04h	04h
3	Number of Row Addresses	11	0Bh	0Bh	0Bh
4	Number of Column Addresses	8	08h	08h	08h
5	Number of Module Banks	1 bank	01h	01h	01h
6	Data Width	64 bit	40h	40h	40h
7	Data Width (Continuation)	+0	00h	00h	00h
8	Interface Type	LVTTL	01h	01h	01h
9	SDRAM Cycle Time (Highest CAS Latency)	10/12/15 ns	A0h	C0h	F0h
10	SDRAM Access from Clock (Highest CAS Latency)	8.5/8.5/9 ns	85h	85h	90h
11	DIMM Configuration Type	Non-Parity	00h	00h	00h
12	Refresh Rate/Type	Self, Normal	80h	80h	80h
13	Primary SDRAM Width	×16	10h	10h	10h
14	Error Checking SDRAM Width	0	00h	00h	00h
15	Minimum Clock Delay for Back to Back Random Column	1 Cycle	01h	01h	01h
	Addresses				
16	Burst Lengths Supported	1, 2, 4, 8, Page	8Fh	8Fh	8Fh
17	Number of Banks on Each SDRAM Device	2 bank	02h	02h	02h
18	CAS Latency	2, 3	06h	06h	06h
19	CS Latency	0	01h	01h	01h
20	Write Latency	0	01h	01h	01h
21	SDRAM Module Attributes	UN-buffer	00h	00h	00h
22	SDRAM Device Attributes	*1	06h	06h	06h
23	SDRAM Cycle Time (2nd. Highest CAS Latency)	15/17/20 ns	F0h	20h	FFh
24	SDRAM Access from Clock (2nd. Highest CAS Latency)	9/9/10 ns	90h	90h	A0h
25	SDRAM Cycle Time (3rd. Highest CAS Latency)	No Support	00h	00h	00h
26	SDRAM Access from Clock (3rd. Highest CAS Latency)	No Support	00h	00h	00h
27	Precharge to Activate Min. (trp)	30/35/40 ns	1Eh	23h	28h
28	Row Activate to Row Activate Min. (trrd)	30/30/30 ns	1Eh	1Eh	1Eh
29	RAS to CAS Delay Min. (trcd)	30/30/30 ns	1Eh	1Eh	1Eh
30	Activate to Precharge Minimum Time (tras)	60/65/70 ns	3Ch	41h	46h
31	Module Bank Density	8 MByte	02h	02h	02h
32 to 61	Unused Storage Locations		00h	00h	00h
62	SPD Data Revision Code	1	01h	01h	01h
63	Checksum for Byte 0 to 62	*2	4Fh	A9h	DDh
64 to 98	Manufacturer's Information: Unused Storage	_	00h	00h	00h
99 to 127		_	00h	00h	00h
128+	Unused Storage Locations	_	_	_	_

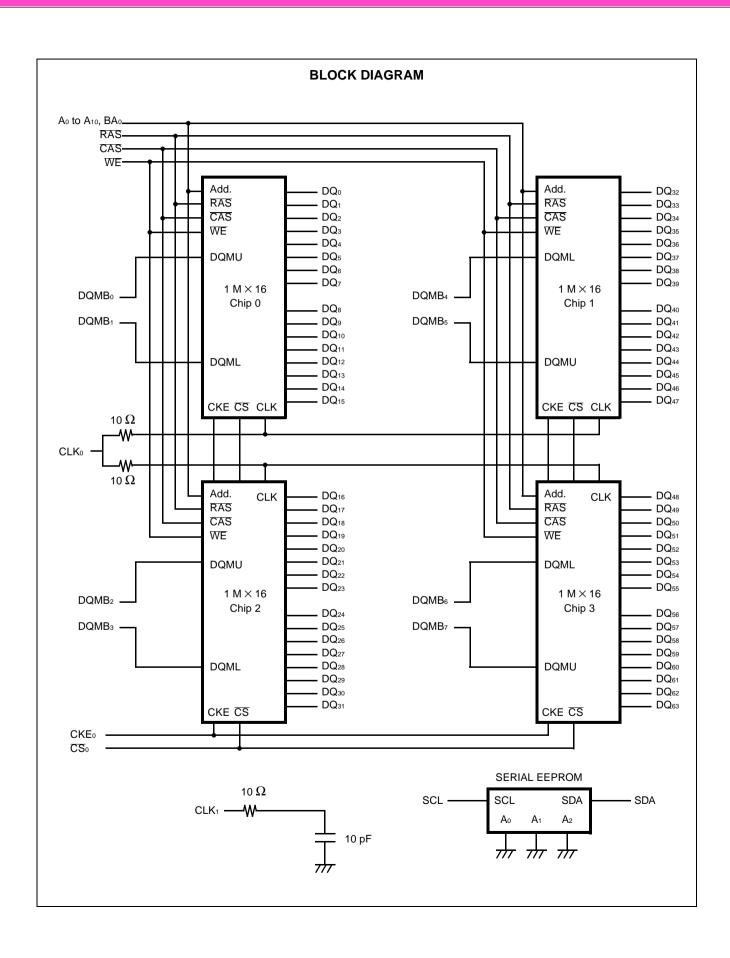
Note: Any write operation must NOT be executed into the addresses of Byte 0 to Byte 127. Some or all data stored into Byte 0 to Byte 127 may be broken.

*1. SDRAM Device Attributes

Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
TBD	TBD	Upper V _{CC} tolerance 0 = 10%	Lower Vcc tolerance 0 = 10%	Supports Write 1/ Read Burst	Supports Precharge All	Supports Auto- Precharge	Supports Early RAS Precharge
0	0	0	0	0	1	1	0

^{*2.} Checksum for Bytes 0 to 62

This byte is the checksum for bytes 0 through 62. This byte contains the value of the low 8-bits of the arithmetic sum of bytes 0 through 62.



■ ABSOLUTE MAXIMUM RATINGS (See WARNING)

Parameter	Symbol	Va	Unit		
Farameter	Symbol	Min.	Max.	Onit	
Supply Voltage*	Vcc	-0.5	+4.6	V	
Input Voltage*	Vin	-0.5	+4.6	V	
Output Voltage*	Vouт	-0.5	+4.6	V	
Storage Temperature	Тѕтс	– 55	+125	O°	
Power Dissipation	Po	_	5.2	W	
Output Current (D.C.)	І оит	-50	+50	mA	

^{*:} Voltages referenced to Vss (= 0 V)

WARNING: Semiconductor devices can be permanently damaged by application of stress (voltage, current, temperature, etc.) in excess of absolute maximum ratings. Do not exceed these ratings.

■ RECOMMENDED OPERATING CONDITIONS

Doromotor	Netes	Cumb al		Unit		
Parameter	Notes	Symbol	Min.	Тур.	Max.	Unit
Cupply Voltage	*1	Vcc	3.0	3.3	3.6	V
Supply Voltage	Ī	Vss	0	0	0	V
Input High Voltage, All Inputs	*1	ViH	2.0	_	Vcc +0.5	V
Input Low Voltage, All Inputs	*1, 2	VIL	-0.5	_	0.8	V
Ambient Temperature		TA	0	_	+70	°C

^{*1.} Voltages referenced to Vss (= 0 V)

WARNING: Recommended operating conditions are normal operating ranges for the semiconductor device. All the device's electrical characteristics are warranted when operated within these ranges.

Always use semiconductor devices within the recommended operating conditions. Operation outside these ranges may adversely affect reliability and could result in device failure.

No warranty is made with respect to uses, operating conditions, or combinations not represented on the data sheet. Users considering application outside the listed conditions are advised to contact their FUJITSU representative beforehand.

^{*2.} $V \perp (min) = -1.5 \text{ V AC (Pulse Width} \leq 5 \text{ ns)}$

■ CAPACITANCE

 $(Vcc = +3.3 \text{ V}, f = 1 \text{ MHz}, T_A = +25^{\circ}\text{C})$

Paramet		Cumbal	Va	lue	Unit
Paramet	ei	Symbol	Min.	Max.	Offic
	A ₀ to A ₁₀ , BA ₀	C _{IN1}	_	25	pF
	RAS, CAS, WE	CIN2	_	26	pF
	CS₀	Сімз	_	24	pF
Input Capacitance	CKE₀	C _{IN4}	_	25	pF
	CLKo, CLK1	CIN5	_	29	pF
	DQMB ₀ to DQMB ₇	CIN6	_	12	pF
	SCL	Cscl	_	7	pF
Input/Output Capacitance	SDA	CSDA	_	7	pF
Input/Output Capacitance	DQ ₀ to DQ ₆₃	CDQ	_	13	pF

■ DC CHARACTERISTICS

(At recommended operating conditions unless otherwise noted.)

				0 1111	Va	lue	
Parameter N	otes		Symbol	Condition	Min.	Max.	Unit
		MB8501S064AE-100		No Burst;		340	mA
		MB8501S064AE-84	Icc1s	tck = min	_	320	mA
Operating Current	*1	MB8501S064AE-67		One Bank Active		300	mA
(Average Power Supply Current)	1	MB8501S064AE-100		No Burst;		520	mA
,,,,		MB8501S064AE-84	Icc1D	tck = min trc = min	_	480	mA
		MB8501S064AE-67		All Banks Active		440	mA
Precharge Standby Current (Power	*1		Ісс2Р	CKE = VIL, tck = min All Banks Idle	_	8	mA
Supply Current)	1		ICC2N	CKE = V _{IH} , tck = min All Banks Idle	_	120	mA
Active Standby Current (Power	*1		Іссзр	CKE = V _{IL} , t _{CK} = min Any Bank Active	_	120	mA
Supply Current)	ı		Іссзи	CKE = Vін, tcк = min Any Bank Active	_	200	mA
Burst Mode Current		MB8501S064AE-100			_	540	mA
(Average Power	*1	MB8501S064AE-84	Icc4	tck = min	_	500	mA
		MB8501S064AE-67			_	460	mA
Auto-refresh Current		MB8501S064AE-100		Auto Refresh	_	440	mA
(Average Power	*1	MB8501S064AE-84	Icc5	tck = min trc = min	_	400	mA
Supply Current)		MB8501S064AE-67		trrd = min	_	360	mA
Self-refresh Current (Average Power Supply	Curre	nt)	Icc ₆	CKE = VIL	_	8	mA
Input Leakage Current (All In		outs)	lı (L)	$0 \text{ V} \le \text{V}_{\text{IN}} \le \text{V}_{\text{CC}}$ All other pins not under test = 0 V $3.0 \text{ V} \le \text{V}_{\text{CC}} \le 3.6 \text{ V}$	-30	30	μΑ
Output Leakage Current			lo (L)	Output is disabled (Hi-Z) $0 \text{ V} \leq \text{V}_{\text{IN}} \leq \text{V}_{\text{CC}}$ $3.0 \text{ V} \leq \text{V}_{\text{CC}} \leq 3.6 \text{ V}$	-10	10	μΑ
LVTTL Output High Voltage	*2		Vон	lон = −2.0 mA	2.4	_	V
LVTTL Output Low Voltage	*2		Vol	IoL = +2.0 mA	_	0.4	V

Notes: *1. lcc depends on the output termination, load conditions, clock cycle rate and signal clock rate. The specified values are obtained with the output open and no termination register.

- *2. Voltages referenced to Vss (= 0 V)
- *3. An initial pause (DESL on NOP) of 200 μ s is required after power-on followed by a minimum of eight Auto-refresh cycles.
- *4. DC characteristics is the Serial PD standby state (V_{IN} = GND or V_{CC}).

■ AC CHARACTERISTICS

(1) BASE CHARACTERISTICS

(At recommended operating conditions unless otherwise noted.)

No.	Parameter Notes		Symbol	MB8501 -1	S064AE 00		S064AE 34		S064AE 57	Unit
				Min.	Max.	Min.	Max.	Min.	Max.	
1	Clock Period	CL = 3	tck	10	_	12	_	15	_	ns
'	Clock Period	CL = 2	LOK	15	_	17	_	20	_	ns
2	Clock High Time		tсн	4	_	4	_	4	_	ns
3	Clock Low Time		t CL	4	_	4	_	4	_	ns
4	CS Setup Time		tsc	3	_	3	_	3	_	ns
5	CS Hold Time		tнc	1	_	1	_	1	_	ns
6	Input Setup Time		t sı	3	_	3	_	3	_	ns
7	Input Hold Time		tнı	1	_	1	_	1	_	ns
8	Data Input Setup Time		tsid	3	_	3	_	3	_	ns
9	Data Input Hold Time		t HID	1	_	1	_	1	_	ns
	Output Valid	CL = 3	_	_	8.5	_	8.5	_	9	
10	from Clock *1, *2 (tclk = min)	CL = 2	t AC		9	_	9	_	10	ns
11	Output in Low-Z		tolz	3		3		3	_	ns
12	Output in High-Z *3		t onz	3	_	3	_	3	_	ns
13	Output Hold Time		tон	3	_	3	_	3	_	ns
14	Time between Refresh		t REF	_	32.8	_	32.8	_	32.8	ms
15	Transition Time		tτ	0.5	2	0.5	2	0.5	2	ns
16	Power Down Exit Time		t PDE	3	_	4	_	5	_	ns

(2) BASE VALUES FOR CLOCK COUNT/LATENCY

No.	Parameter	Notes	Symbol	MB8501S064AE -100		MB8501S064AE -84		MB8501	Unit	
				Min.	Max.	Min.	Max.	Min.	Max.	
1	RAS Cycle Time	*4	t RC	90	_	100	_	110	_	ns
2	RAS Access Time	*5	t rac		54		56		60	ns
3	CAS Access Time	*6, *9	t cac		24		26		30	ns
4	RAS Precharge Time		t RP	30	_	35	_	40	_	ns
5	RAS Active Time		t RAS	60	100000	65	100000	70	100000	ns
6	RAS to CAS Delay Time	*7	t RCD	30	_	30	_	30	_	ns
7	Write Recovery Time		t wr	10	_	12	_	15	_	ns
8	Write Precharge Time		t rwL	10	_	12	_	15	_	ns
9	RAS to CAS Bank Active Delay Time		t rrd	30	_	30	_	30	_	ns

(3) CLOCK COUNT FORMULA (*8)

$$Clock \ge \frac{\text{Base Value}}{\text{Clock Period}} \text{ (Round off a whole number)}$$

(4) LATENCY (The latency values on these parameters are fixed regardless of clock period.)

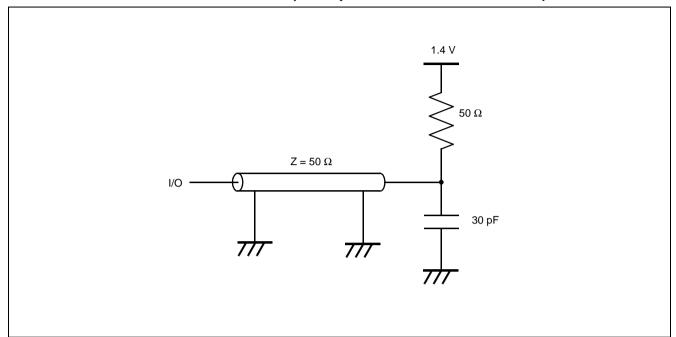
No.	Parameter		Symbol	MB8501S064AE -100	MB8501S064AE -84	MB8501S064AE -67	Unit
1	CKE to Clock Disable		Іске	1	1	1	Cycle
2	DQM to Output in High-Z	•	ldQz	2	2	2	Cycle
3	DQM to Input Data Delay	1	IDQD	0	0	0	Cycle
4	Last Output to Write Command Delay		lowd	2	2	2	Cycle
5	Write Command to Input Data Delay		I DWD	0	0	0	Cycle
6	Precharge to	CL = 3	I=	3	3	3	Cycle
0	Output in High-Z Delay	CL = 2	Iroh	2	2	2	Cycle
7	Mode Register Access to Bank Active (min)		I MRD	2	2	2	Cycle
8	CAS to CAS Delay (min)		Іссь	1	1	1	Cycle
9	CAS Bank Delay (min)		Ісво	1	1	1	Cycle

Notes: *1. Assumes trop and toac are satisfied.

- *2. tac also specifies the access time at burst mode except for first access.
- *3. Specified where output buffer is no longer driven.
- *4. Actual clock count of trc (IRc) will be sum of clock count of tras (IRAS) and trp (IRP).
- *5. trac is a reference value. Maximum value is obtained from the sum of trcd (min) and tcac (max).
- *6. Assumes trac and tac are satisfied.
- *7. Operation within the trop (min) ensures that trac can be met; if trop is greater than the specified trop (min), access time is determined by toac and tac.
- *8. All base values are measured from the clock edge at the command input to the clock edge for the next command input.
 - All clock counts are calculated by a simple formula:
 - clock count equals base value divided by clock period (round off to a whole number).
- *9. The Icac (CAS latency: CL) is programmed by the mode register.
- *10. An initial pause (DESL on NOP) of 200 μs is required after power-up followed by a minimum of eight Auto-refresh cycles.
- *11. 1.4 V or VREF is the reference level for measuring timing of signals. Transition times are measured between V_{IH} (min) and V_{IL} (max).
- *12. AC characteristics assume $t_T = 1$ ns and 30 pF of capacitive load.

*Source: See MB811171622A Data Sheet for details on the electricals.

■ AC OPERATING TEST CONDITION (Example of AC Test Load Circuit)



■ SERIAL PRESENCE DETECT(SPD) FUNCTION

1. PIN DESCRIPTIONS

SCL (Serial Clock)

SCL input is used to clock all data input/output of SPD

SDA (Serial Data)

SDA is a common pin used for all data input/output of SPD. The SDA pull-up resistor is required due to the open-drain output.

SA₀, SA₁, SA₂ (Address)

Address inputs are used to set the least significant three bits of the eight bits slave address. The address inputs must be fixed to select a particular module and the fixed address of each module must be different each other. For this module, any address inputs are not required because all addresses (SA₀, SA₁, SA₂) are driven to Vss on the module.

2. SPD OPERATIONS

CLOCK and DATA CONVENTION

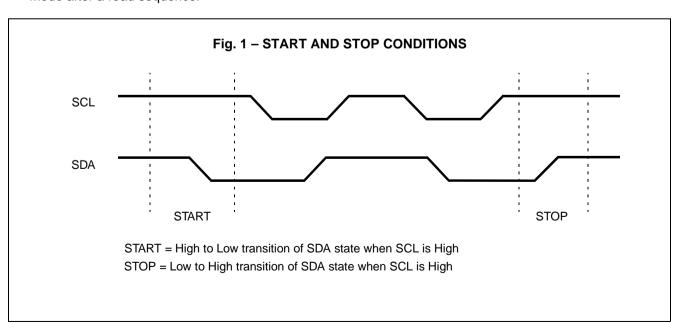
Data states on the SDA can change only during SCL = Low. SDA state changes during SCL = High are indicated start and stop conditions. Refer to Fig. 1 below.

START CONDITION

All commands are preceded by a start condition, which is a transition of SDA state from High to Low when SCL = High. SPD will not respond to any command until this condition has been met.

STOP CONDITION

All read or write operation must be terminated by a stop condition, which is a transition of SDA state from Low to High when SCL = High. The stop condition is also used to make the SPD into the state of standby power mode after a read sequence.



ACKNOWLEDGE

Acknowledge is a software convention used to indicate successful data transfer. The transmitting device, either master or slave, will release the bus after transmitting eight bits. During the ninth clock cycle the receiver will put the SDA line to Low in order to acknowledge that it received the eight bits of data.

The SPD will respond with an acknowledge when it received the start condition followed by slave address issued by master.

In the read operation, the SPD will transmit eight bits of data, release the SDA line and monitor the line for an acknowledge. If an acknowledge is detected and no stop condition is issued by master, the SPD will continue to transmit data. If an acknowledge is not detected, the SPD will terminated further data transmissions. The master must then issue a stop condition to return the SPD to the standby power mode.

In the write operation, upon receipt of eight bits of data the SPD will respond with an acknowledge, and await the next eight bits of data, again reponding with an acknowledge until the stop condition is issued by master.

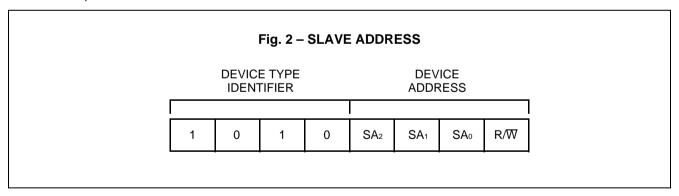
SLAVE ADDRESS ADDRESSING

Following a start condition, the master must output the eight bits slave address. The most significant four bits of the slave address are device type identifier. For the SPD this is fixed as 1010[B]. Refer to the Fig. 2 below.

The next three significant bits are used to select a particular device. A system could have up to eight SPD devices —namely up to eight modules— on the bus. The eight addresses for eight SPD devices are defined by the state of the SA₀, SA₁ and SA₂ inputs. For this module, the three bits are fixed as 000[B] because all addresses are driven to Vss on the module. Therefore, no address inputs are required.

The last bit of the slave address defines the operation to be performed. When R/W bit is "1", a read operation is selected, when R/W bit is "0", a write operation is selected.

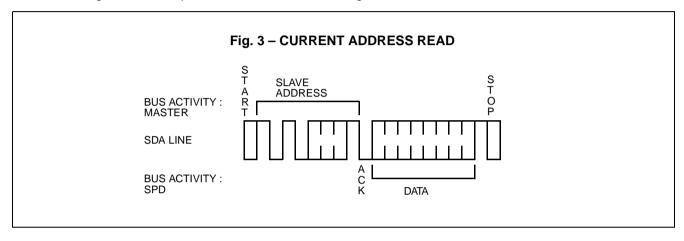
Following the start condition, the SPD monitors the SDA line comparing the slave address being transmitted with its slave address (device type and state of SA₀, SA₁, and SA₂ inputs). Upon a correct compare the SPD outputs an acknowledge on the SDA line. Depending on the state of the R/W bit, the SPD will execute a read or write operation.



3. READ OPERATIONS

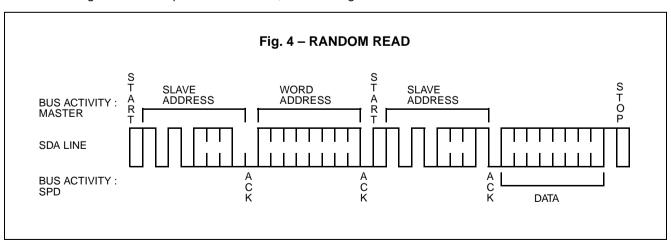
CURRENT ADDRESS READ

Internally the SPD contains an address counter that maintains the address of the last data accessed, incremented by one. Therefore, if the last access (either a read or write operation) was to address(n), the next read operation would access data from address(n+1). Upon receipt of the slave address with the R/ \overline{W} bit = "1", the SPD issues an acknowledge and transmits the eight bits of data during the next eight clock cycles. The master terminates this transmission by issuing a stop condition, omitting the ninth clock cycle acknowledge. Refer to Fig. 3 for the sequence of address, acknowledge and data transfer.



RANDOM READ

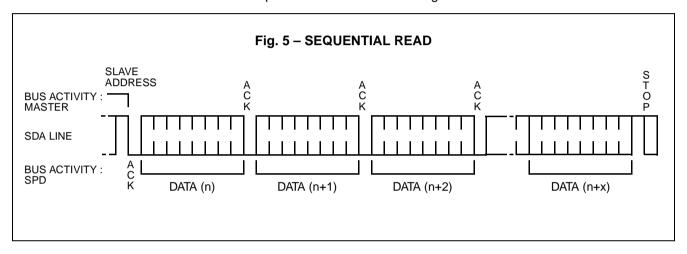
Random Read operations allow the master to access any memory location in a random manner. Prior to issuing the slave address with the R/ \overline{W} bit = "1", the master must first perform a "dummy" write operation on the SPD. The master issues the start condition, and the slave address followed by the word address. After the word address acknowledge, the master immediately reissues the start condition and the slave address with the R/ \overline{W} bit = "1". This will be followed by an acknowledge from the SPD and then by the eight bits of data. The master terminates this transmission by issuing a stop condition, omitting the ninth clock cycle acknowledge. Refer to Fig. 4 for the sequence of address, acknowledge and data transfer.



SEQUENTIAL READ

Sequential Read can be initiated as either a current address read or random read. The first data are transmitted as with the other read mode, however, the master now responds with an acknowledge, indicating it requires additional data. The SPD continues to output data for each acknowledge received. The master terminates this transmission by issuing a stop condition, omitting the ninth clock cycle acknowledge. Refer to Fig. 5 for the sequence of address, acknowledge and data transfer.

The data output is sequential, with the data from address(n) followed by the data from address(n+1). The address counter for read operations increments all address bits, allowing the entire memory contents to be serially read during one operation. At the end of the address space (address 255), the counter "rolls over" to address0 and the SPD continues to output data for each acknowledge received.



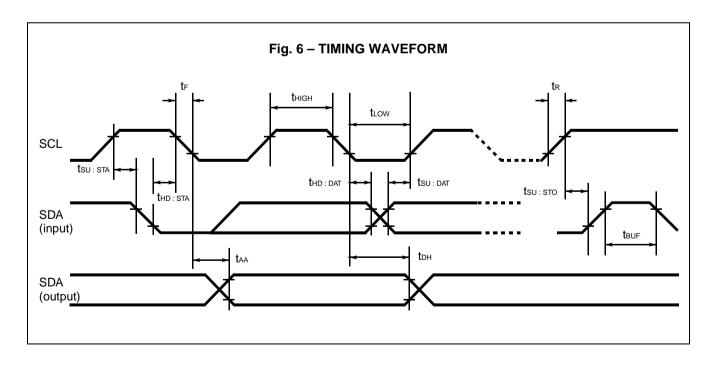
4. DC CHARACTERISTICS

Parameter	Note	Symbol	Condition	Value		Unit
Parameter			Condition	Min.	Max.	Offic
Input Leakage Current		Sili	$0 \text{ V} \leq V_{IN} \leq V_{CC}$	-10	10	μΑ
Output Leakage Current		SILO	0 V ≤ Vouт ≤ Vcc	-10	10	μΑ
Output Low Voltage	*1	Svol	IoL = 3.0 mA	_	0.4	V

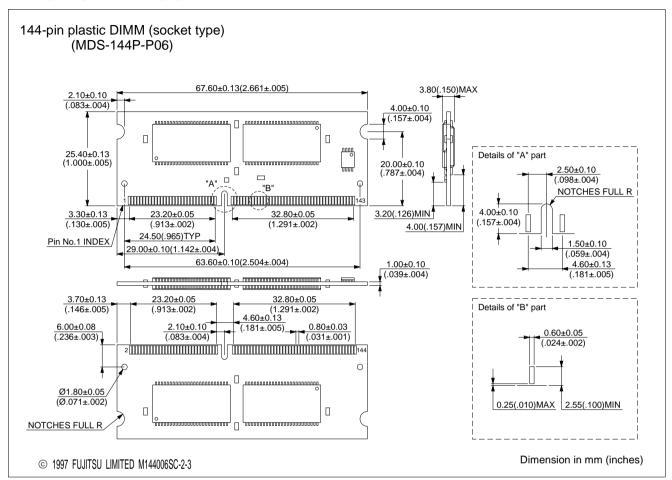
Note: *1. Referenced to Vss.

5. AC CHARACTERISTICS

No.	Doromotor	Symbol	Value		11
	Parameter		Min.	Max.	Unit
1	SCL Clock Frequency	fscL	_	100	KHz
2	Noise Suppression Time Constant at SCL, SDA Inputs	Tı	_	100	ns
3	SCL Low to SDA Data Out Valid	taa	_	3.5	μs
4	Time the Bus Must Be Free Before a New Transmission Can Start	t BUF	4.7	_	μs
5	Start Condition Hold Time	thd:sta	4.0	_	μs
6	Clock Low Period	tLOW	4.7	_	μs
7	Clock High Period	t HIGH	4.0	_	μs
8	Start Condition Setup Time	tsu:sta	4.7	_	μs
9	Data in Hold Time	thd:dat	0	_	μs
10	Data in Setup Time	tsu:dat	250	_	ns
11	SDA and SCL Rise Time	t R	_	1	μs
12	SDA and SCL Fall Time	tr	_	300	ns
13	Stop Condition Setup Time	t su:sto	4.7	_	μs
14	Data Out Hold Time	tон	100	_	ns
15	Write Cycle Time	t wr	_	15	ms



■ PACKAGE DIMENSION



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